

# Jumbo advisory panel for IIT-I workshop

**The committee comprises 11 profs from IIT Madras, 9 from IIT Delhi and 8 from IIT Bombay**

**OUR STAFF REPORTER**  
Indore

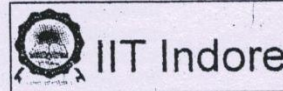
The Indian Institute of Technology Indore has constituted a jumbo advisory committee comprising as many as 57 professors for the second international conference on Intelligent Robotics, Automation and Manufacturing (IRAM) 2013.

The conference would take place from December 16 to 18 at the institute.

The advisory committee includes a total of 49 professors from premier institutes in the country — including 11 professors from IIT Madras, nine from IIT Delhi and eight from IIT Bombay.

Besides, the committee also comprises eight professors from countries viz China, Japan, South Korea and the USA.

The professors from abroad are: Prof Tatsuo Okada from Kyushu University, Japan; Prof Bq Cao from Jinan University, China; Prof Alain YL Chong from Nottingham University Business School China; Prof Jin Whan Kim from KAIST, South Korea;



Prof Daisuke Nakamura from Kyushu University, Japan; Prof KP Rajurkar from University of Nebraska, Lincoln USA; Prof VC Venkatesh from University of Nevada, Las Vegas USA; and Dr Shaomin Wu from University of Kent.

"The IRAM is one of the biggest events of the institute so it constituted a large advisory committee for technical suggestions. Researchers from across the country would participate in the 3-day conference," an officer of the IIT-

Indore told Free Press.

The IRAM-2013 aims at bringing together experts from academic, scientists and industrial communities to address new challenges, presents their latest research findings, ideas, development and perspectives of the future directions in the fields of Robotics, Automation and Manufacturing.

The IIT Indore has another big conference scheduled for December. This conference is on "nonlinear systems and dynamics" and would be attended by as many as 15 professors from foreign countries such as the USA, Germany, China, Taiwan, Singapore etc.